





#### Course: After Gaudí

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Contribution: Computational Modeling | Robotic Stereotomy | Fabrication | Grasshopper Scripting | Presentation

#### Abstract:

The project "Varmalaug," presented in our design seminar, explores the intricate relationship between climate analysis and form optimization, drawing inspiration from the teachings of Antoni Gaudí. Gaudí's unique approach to deriving organic forms, deeply rooted in the study of nature and geometry, serves as a guiding principle for this project. Varmalaug delves into the complexities of climate data to inform architectural design, ensuring structures that are not only aesthetically pleasing but also highly efficient and sustainable. By integrating Gaudí's principles with modern computational tools, Varmalaug aims to create innovative designs that harmonize with their environment, reflecting both functional excellence and artistic beauty.









Antoni Gaudí revolutionized architecture by using natural geometries, particularly hyperboloids and doubly curved surfaces, to create flowing, organic structures. These forms provided both beauty and structural integrity, evident in masterpieces like the Sagrada Família.

## **HYPERBOLOIDS**

INTERACTION: P Length: 0.60 units Q Length: 0.60 units

Asymptote: 23.00°

Depth: 1.20 unit

## PLASTER MODELS:

















## REMBRANDT ANALYSIS:

Intersecting hyperboloids create complex, stable geometries with unique openings that allow natural light to penetrate walls. These intersections form intricate patterns that diffuse light, casting dynamic shadows and illuminating spaces. This design leverages natural light for a visually captivating and energy-efficient architectural experience.

Hyperboloid A: P Length: 0.13 units

Q Length: 0.27 units Asymptote: 42.00° Depth: 1.00 unit

Hyperboloid B:

P Length: 0.10 units Q Length: 0.20 units Asymptote: 50.00° Depth: 1.00 unit

































Hyperboloid A:



Hyperboloid B:









# GRID



#### GRID OVERLAY:

Overlaying the grid on the surface for further environmental optimization and hyperboloid placement via grid control points.



Initial Spatial Mass

**Optimize Wind Flow** 

## **REPROGRAMMING PERFORATION** PLANES :

Optimizing hyperboloid planes involves strategically creating perforations based on wind direction, incident radiation, and the orientation of the planes. By carefully considering these factors, the design ensures that the structure receives ample sunlight for heating purposes while minimizing unwanted airflow from the outside to the inside. This approach not only enhances the thermal efficiency of the building but also contributes to a comfortable indoor environment by reducing drafts and maintaining a stable internal temperature.

### FORM **DEVELOPMENT**:

Developing the form from a flat surface to a doubly curved surface, through precise control points for better form optimization, ensuring a smooth surface without overlaps or errors.



The form of Varmalaug is inspired by The form is design to make use Iceland's landscape elements - the rugged mountains and volcanoes.

![](_page_2_Picture_14.jpeg)

of the natural hot springs and geothermal rivers.

![](_page_2_Picture_16.jpeg)

Borealis, also known as the Northern Lights.

![](_page_2_Picture_18.jpeg)

**Orienting XY Axis to Wind Direction** 

![](_page_2_Picture_20.jpeg)

![](_page_2_Picture_21.jpeg)

Initial Spatial Mass

**Ruled Surface** 

![](_page_2_Picture_24.jpeg)

**Ruled Surface Continuous** 

Interpolated Curve Continuous

![](_page_2_Picture_27.jpeg)

![](_page_2_Picture_31.jpeg)

![](_page_2_Picture_32.jpeg)

**Optimize Solar Radiation** 

**Defining Access Points** 

![](_page_2_Picture_35.jpeg)

Identifying Existing Plane Normals

![](_page_2_Picture_37.jpeg)

**Orienting Highest Incident Radiation** 

![](_page_2_Picture_39.jpeg)

Approximating Shift in Planes

![](_page_3_Figure_1.jpeg)

## Reprogrammed Hyperboloid Catalogue :

RADIATION ANALYSIS

![](_page_3_Picture_4.jpeg)

BEFORE OPTIMIZATION

![](_page_3_Picture_6.jpeg)

AFTER OPTIMIZATION

![](_page_3_Picture_8.jpeg)

![](_page_3_Picture_9.jpeg)

![](_page_3_Picture_10.jpeg)

![](_page_3_Picture_11.jpeg)

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#### Yuvraj Shirke ROBOTIC STEREOTOMY:

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![](_page_4_Figure_2.jpeg)

![](_page_4_Picture_3.jpeg)

![](_page_4_Picture_4.jpeg)

![](_page_4_Picture_5.jpeg)

![](_page_4_Picture_6.jpeg)

![](_page_4_Picture_7.jpeg)

![](_page_4_Picture_8.jpeg)

![](_page_4_Picture_9.jpeg)

![](_page_4_Picture_10.jpeg)

![](_page_4_Picture_11.jpeg)

![](_page_4_Picture_12.jpeg)